

# A Wildlife Simulation Package

## WISP

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University  
of  
St Andrews

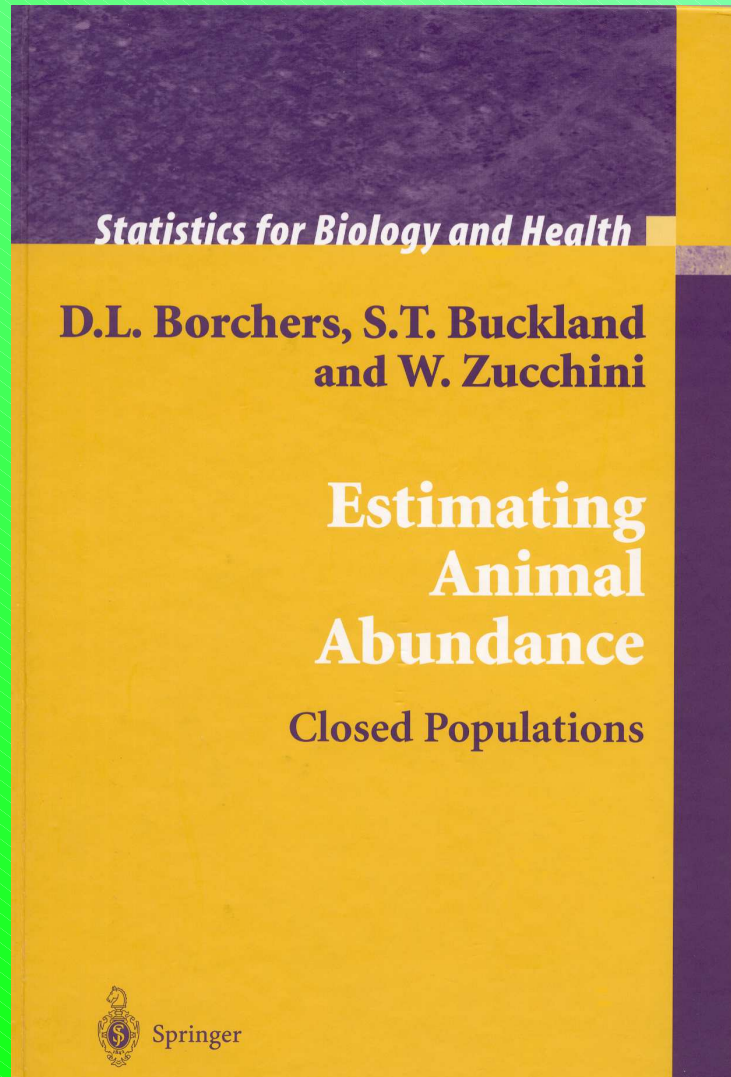
<sup>2</sup> University of St. Andrews

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# Wildlife Simulation Package

**Illustrates the concepts and methodology in:**



**WISP** is a library for R



**CRAN**

The Comprehensive  
R Archive Network

# Wildlife Simulation Package

**A software package that**

- **illustrates the concepts in animal abundance estimation**  
State model, observation model
- **simulates all aspects of the modelling methodology**  
Population, survey design, sampling, estimation
- **enables experimentation with assumptions and methods**  
When, why and how models give the wrong answers

# Concepts in animal abundance estimation

## State model

Describes the spatial distribution and characteristics of animals in a region

Who lives here and where are they?

Population: group size, composition (gender, type), position, exposure

## Survey design

Describes the covered region, survey units, effort (observers/traps)

Where, how, and how hard we look.

Survey design: plot sampling, removal methods, mark-recapture, distance sampling, etc.

## Observation model

Describes the probability that animals with given characteristics are detected.

What we assume we are likely to see.

Detection probability: certain, constant, distance dependent, covariate-dependent

# Abundance estimation process in *WiSP*

generate.region

generate.density

region

density

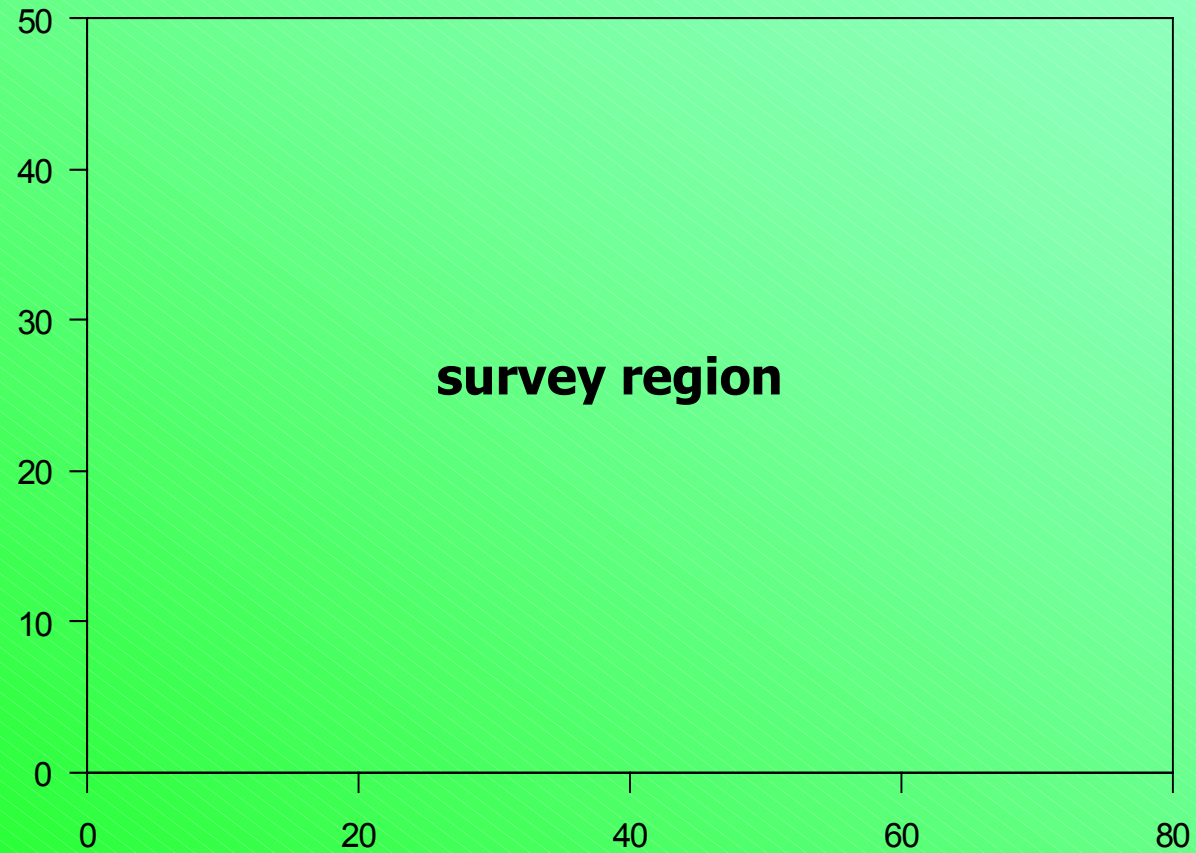
1.) Define survey region  
& population density

functions

objects

# Generating a survey region

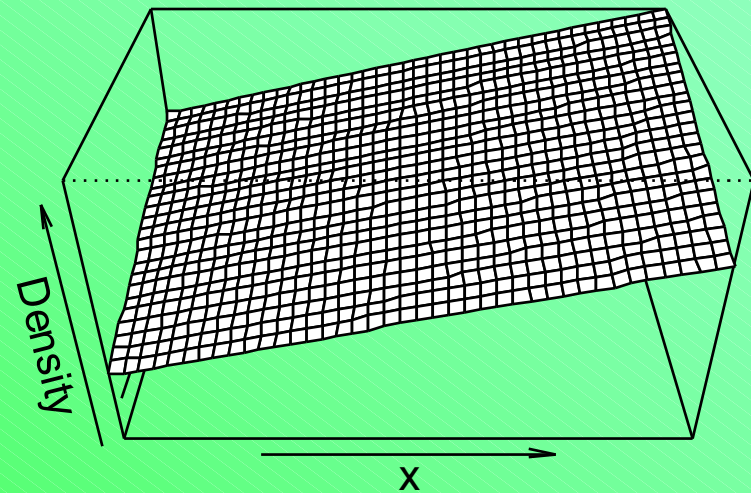
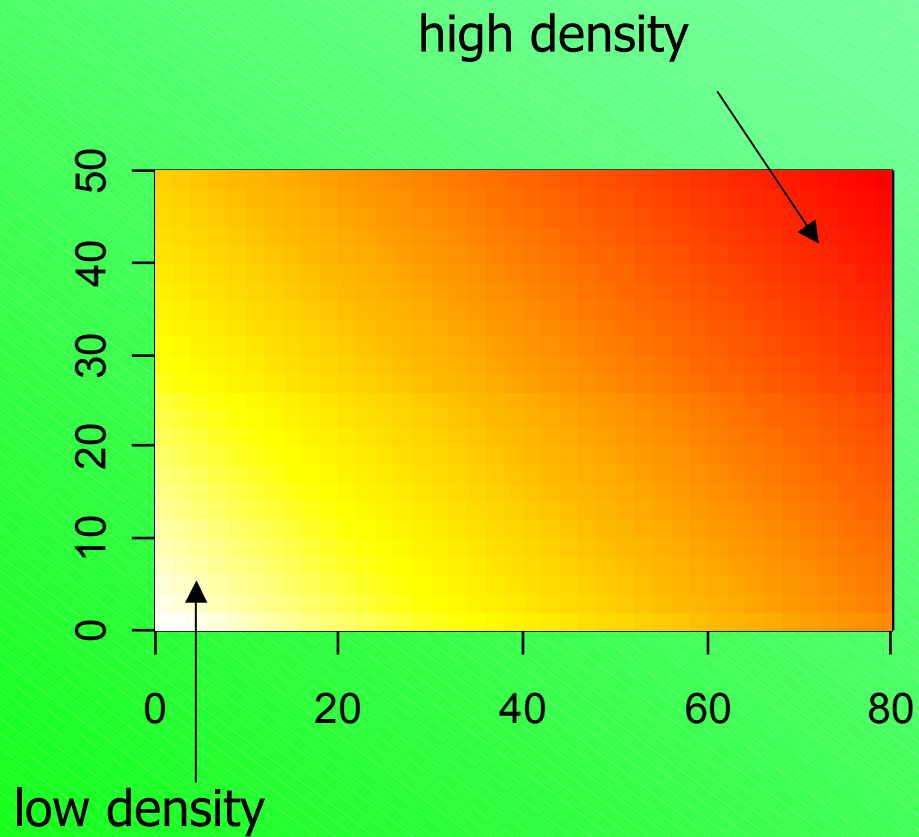
**Survey region = An area of given height and width**



# Generating a population density (1)

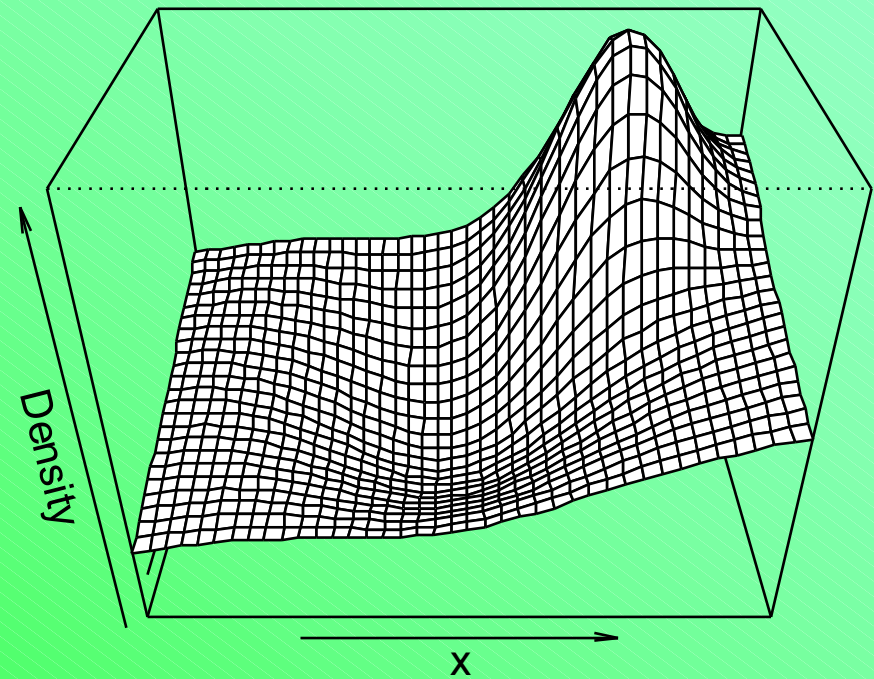
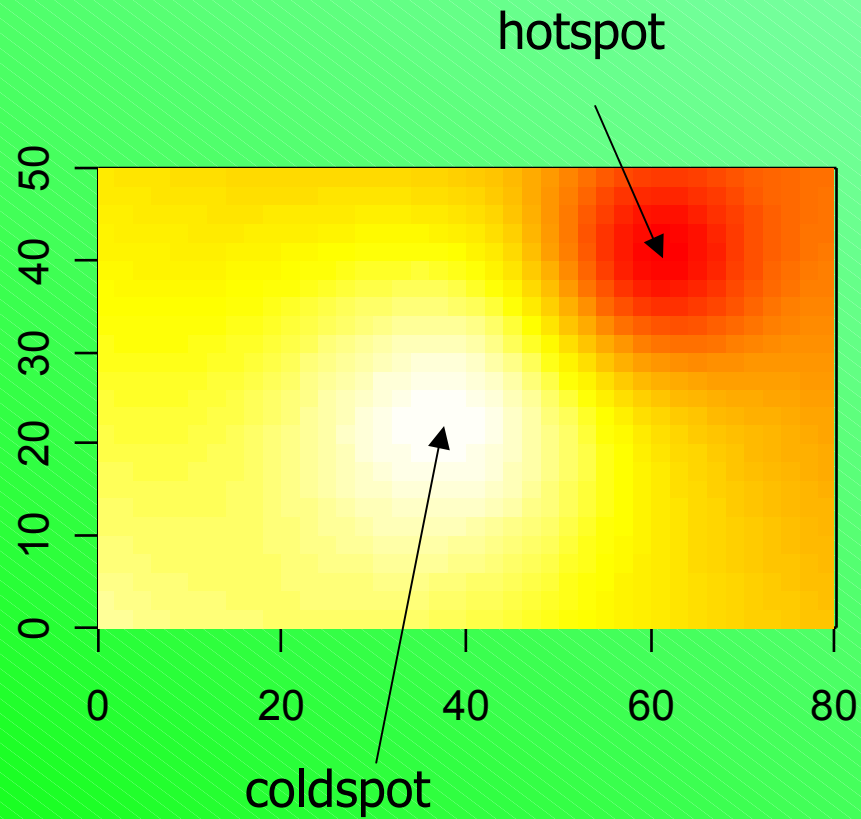
**The population density defines the spatial distribution of animals in the survey region.**

Simple density with linear trend:



# Generating a population density (2)

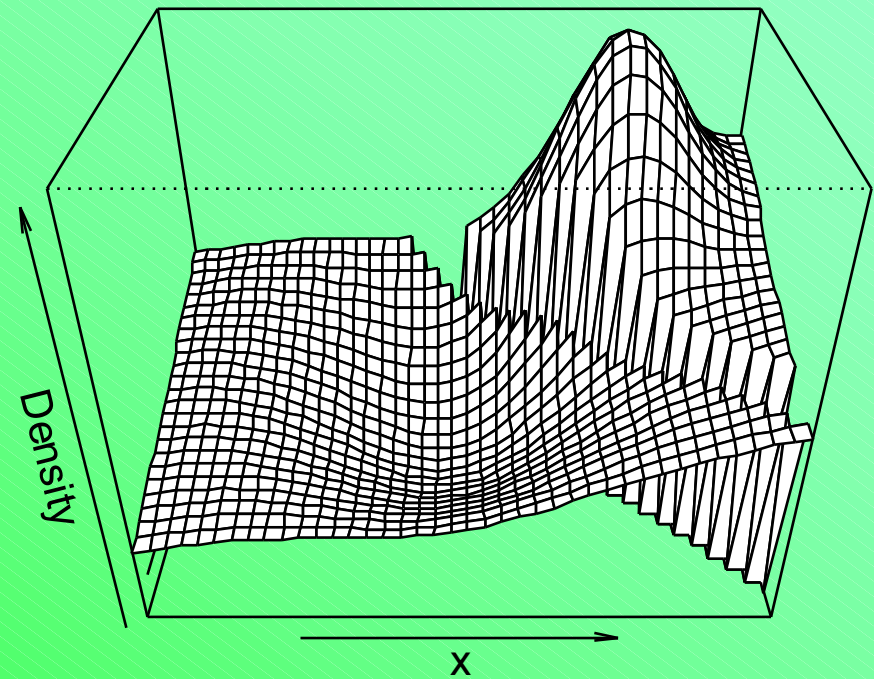
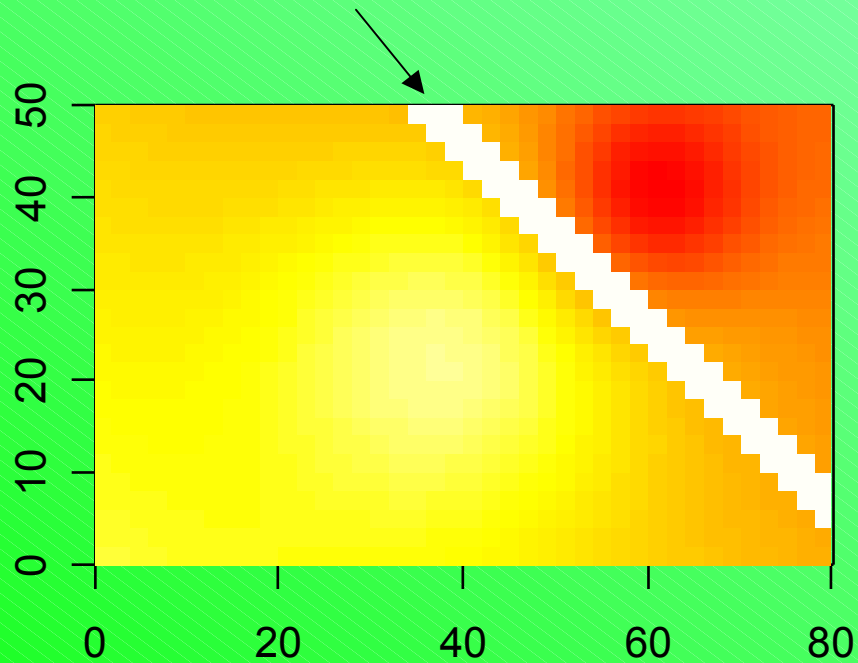
**Increase complexity by adding hotspots and coldspots:**



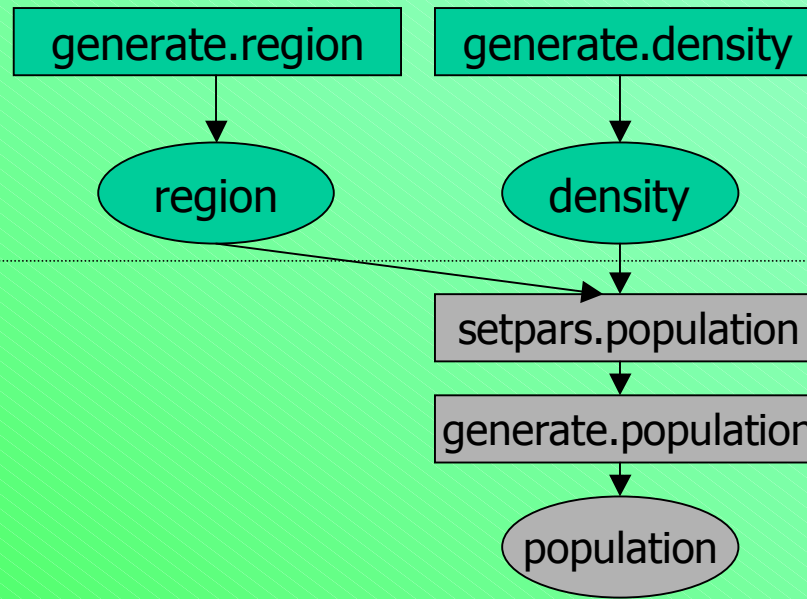
# Generating a population density (3)

**Add more complexity: Strips of constant density**

no animals here



# Abundance estimation process



1.) Define survey region  
& population density

2.) Generate population

functions

objects

# Generating a population

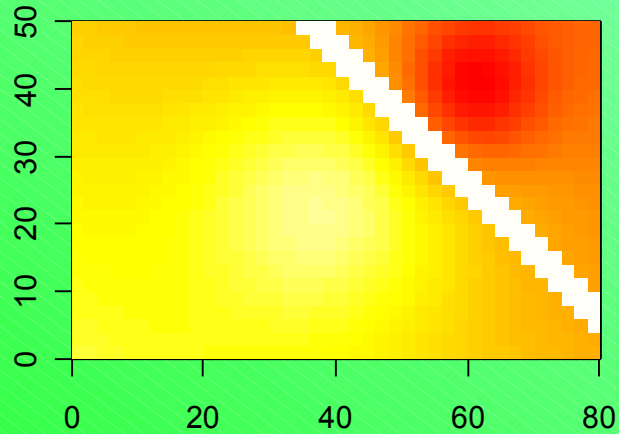
**The population specifies the positions and characteristics of groups and individuals**

## **Population parameters**

- region
- density
- probability distributions of group and individual characteristics (group sizes and exposures)
- number of groups

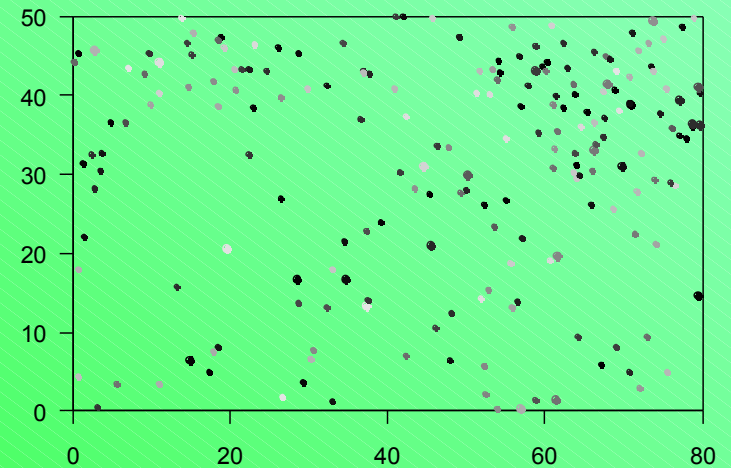
# Generating a population

**region and density**

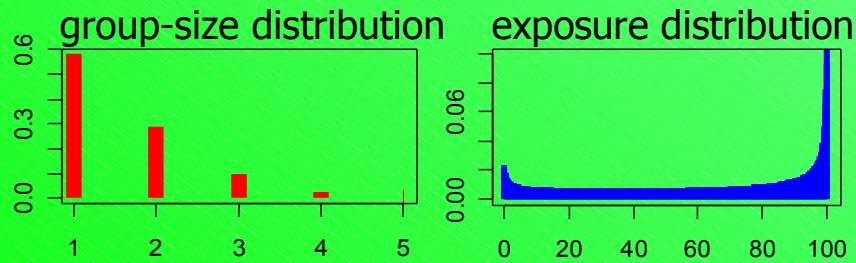


**Generate population**

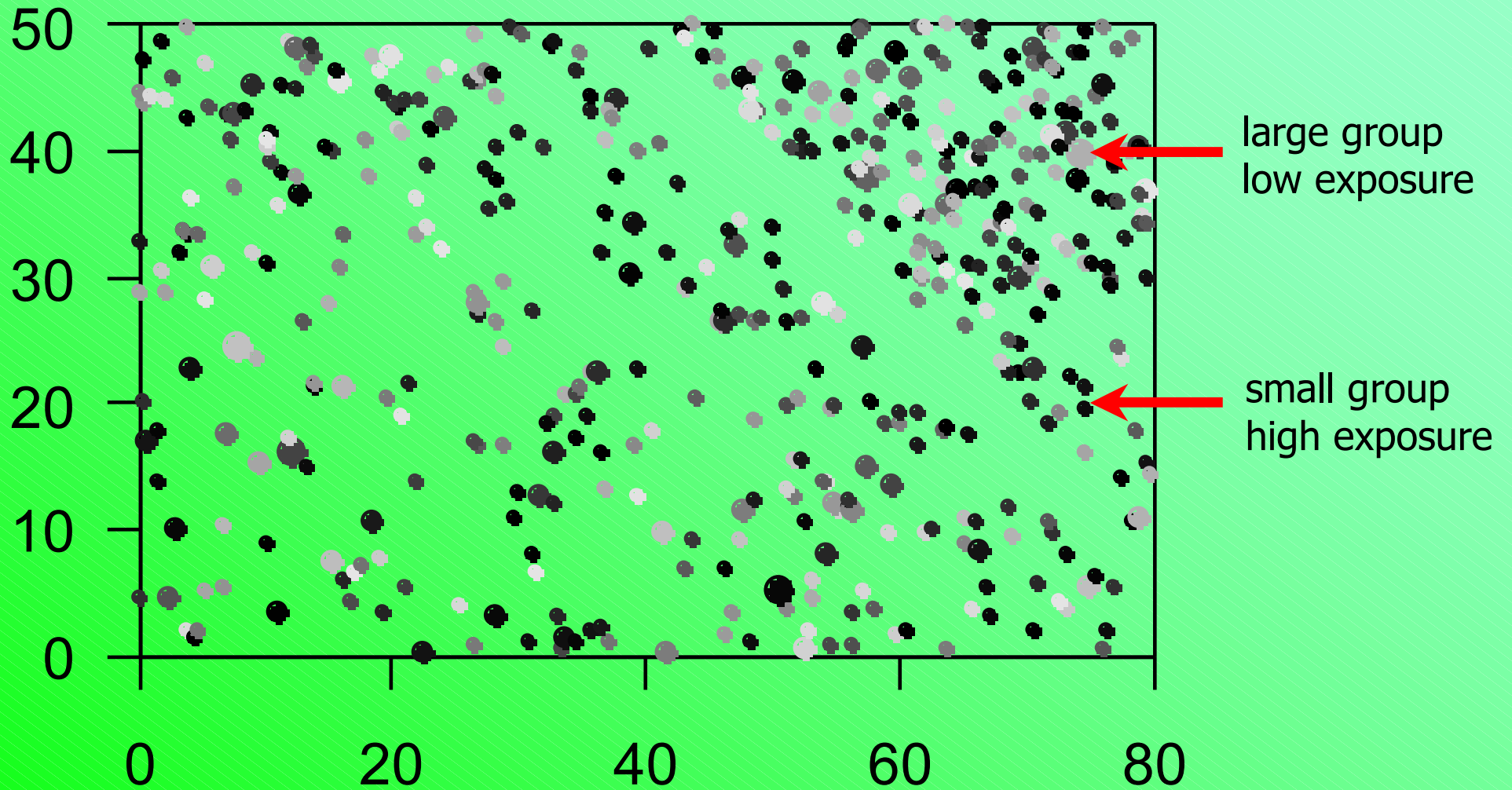
**Population**



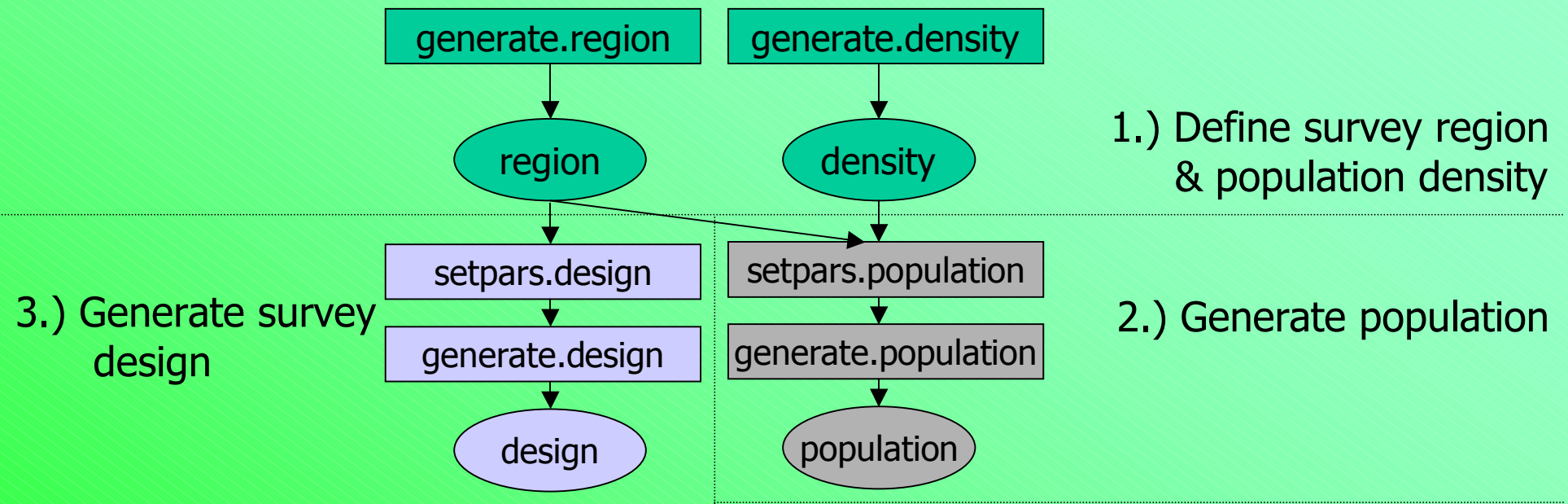
**population parameters**



# A population with 500 groups



# Abundance estimation process in *WiSP*



functions

objects

# Survey designs for closed populations

- **plot sampling**

Count all animals in a selected sub-region

- **removal methods**

simple removal

Repeatedly remove some

catch-effort

& take account of the effort

change-in-ratio

& do so for each type

- **mark-recapture**

various

Repeatedly capture, mark, return

- **distance sampling**

line transect

Count along a transect – record the distances

point transect

Count within a circle – record the distances

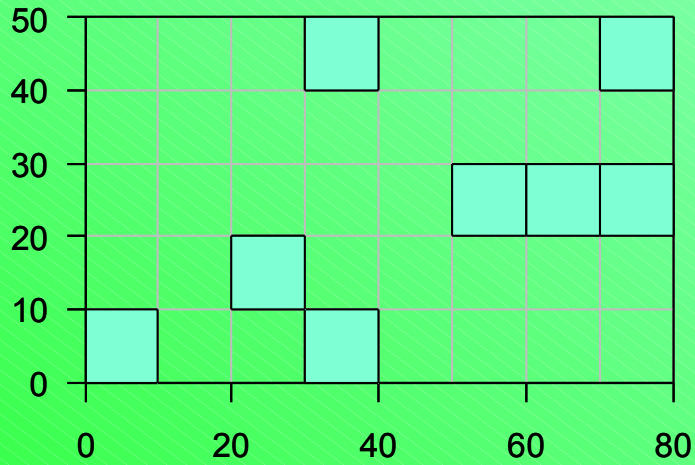
- **nearest object**

single nearest object

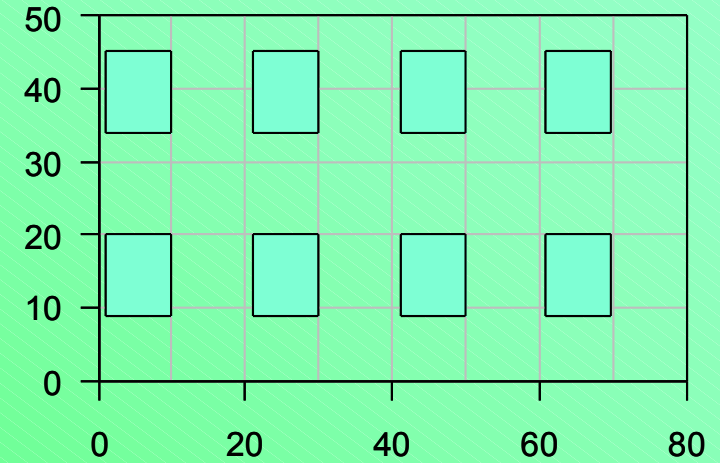
Measure distance to nearest object detected

# Survey designs

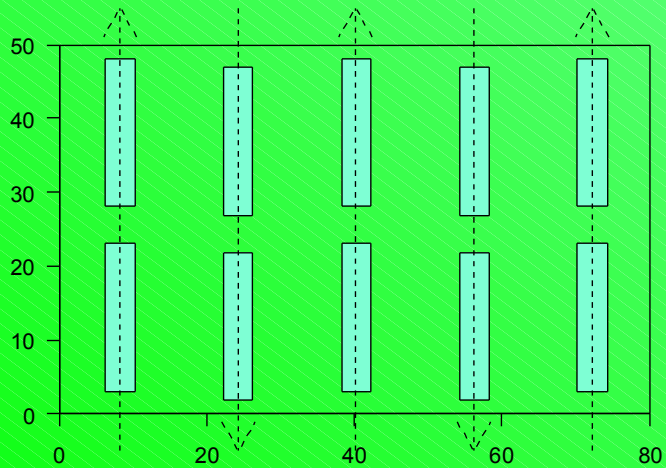
## plot sampling (random)



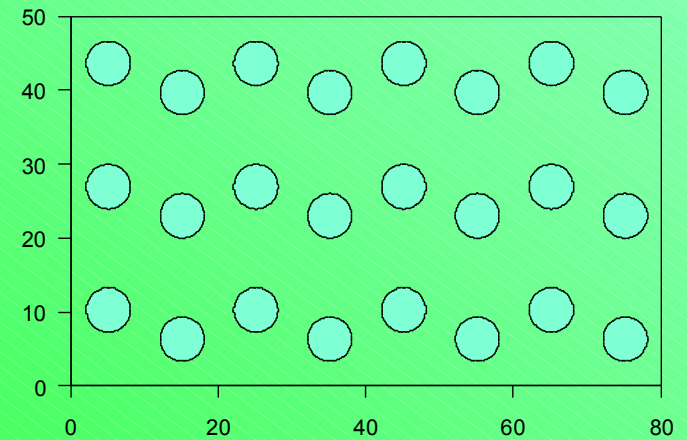
## plot sampling (regular)



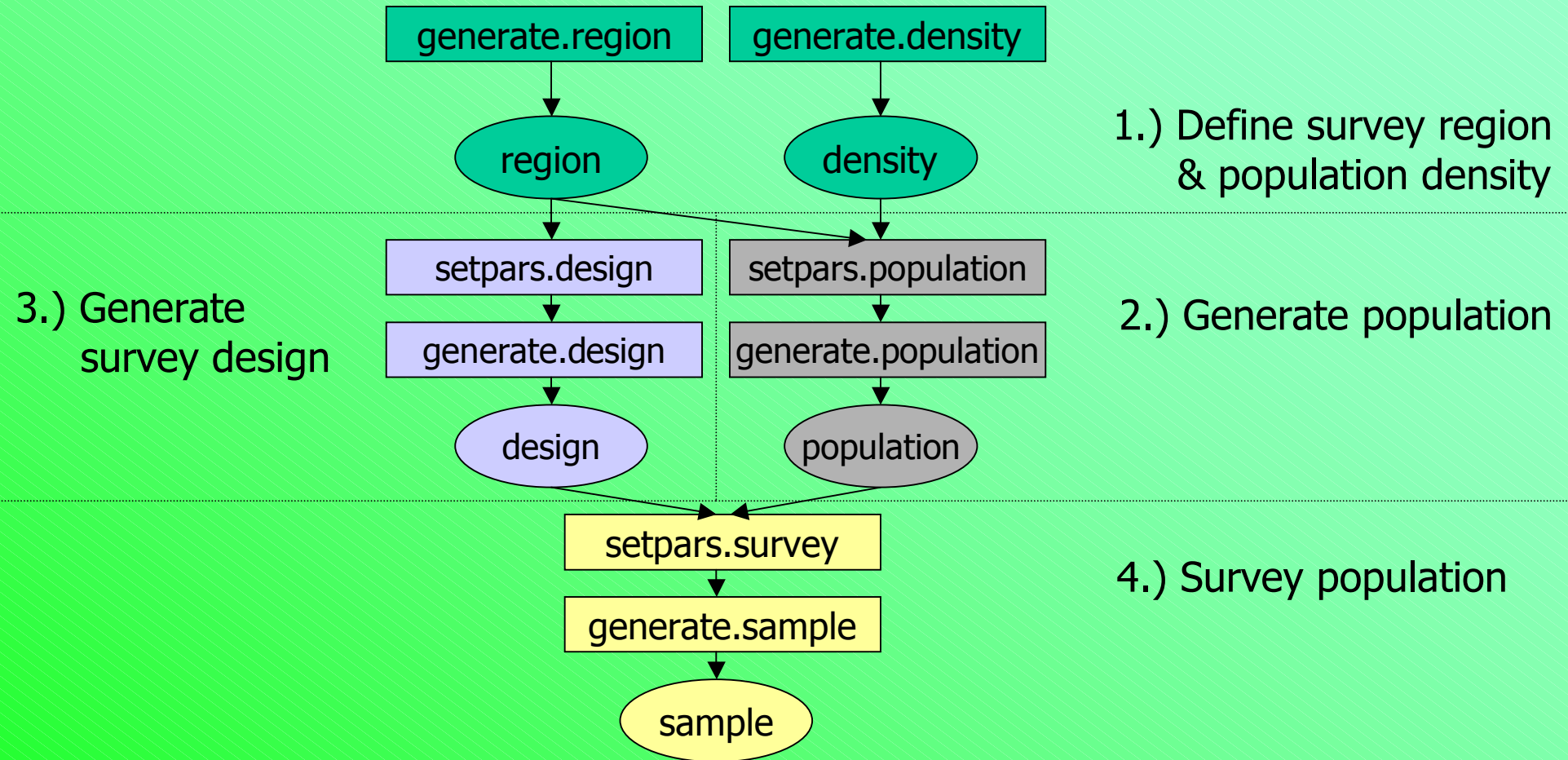
## line transect



## point transect



# Abundance estimation process in *WiSP*

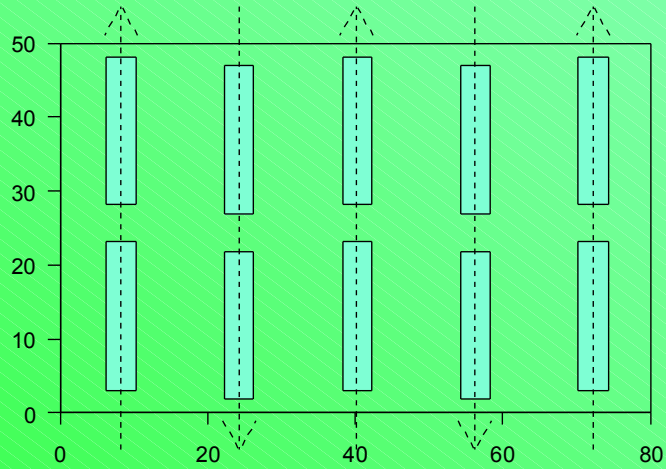


functions

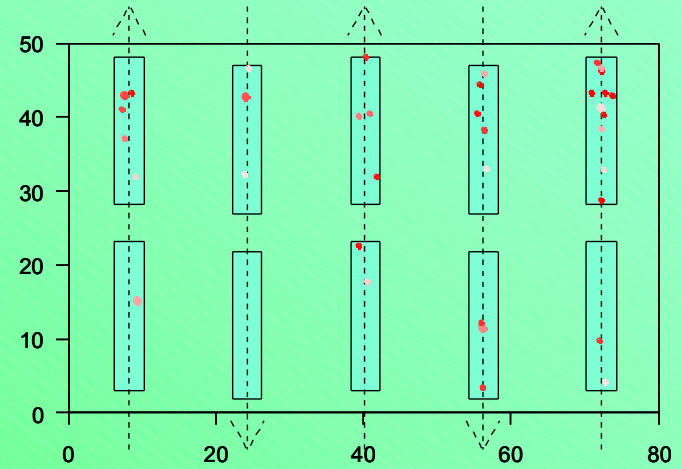
objects

# A line-transect survey

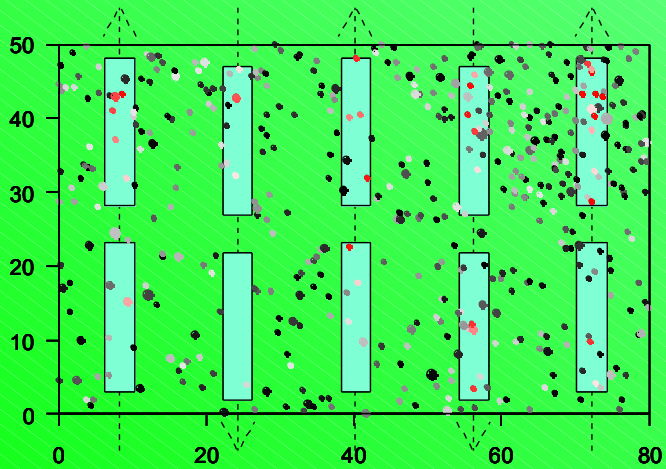
## line-transect design



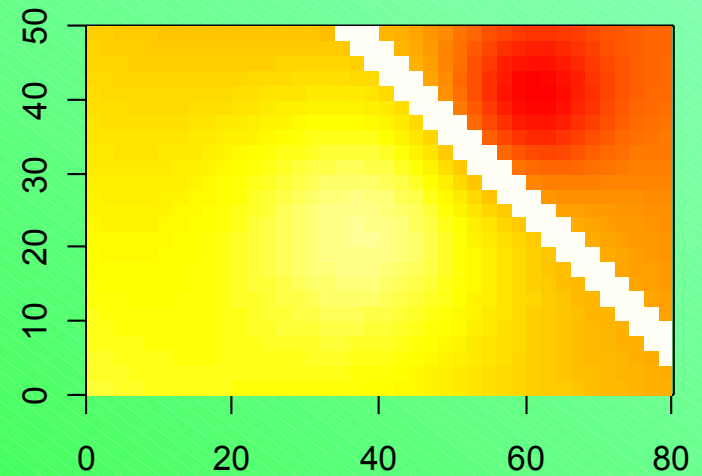
## transects and sample



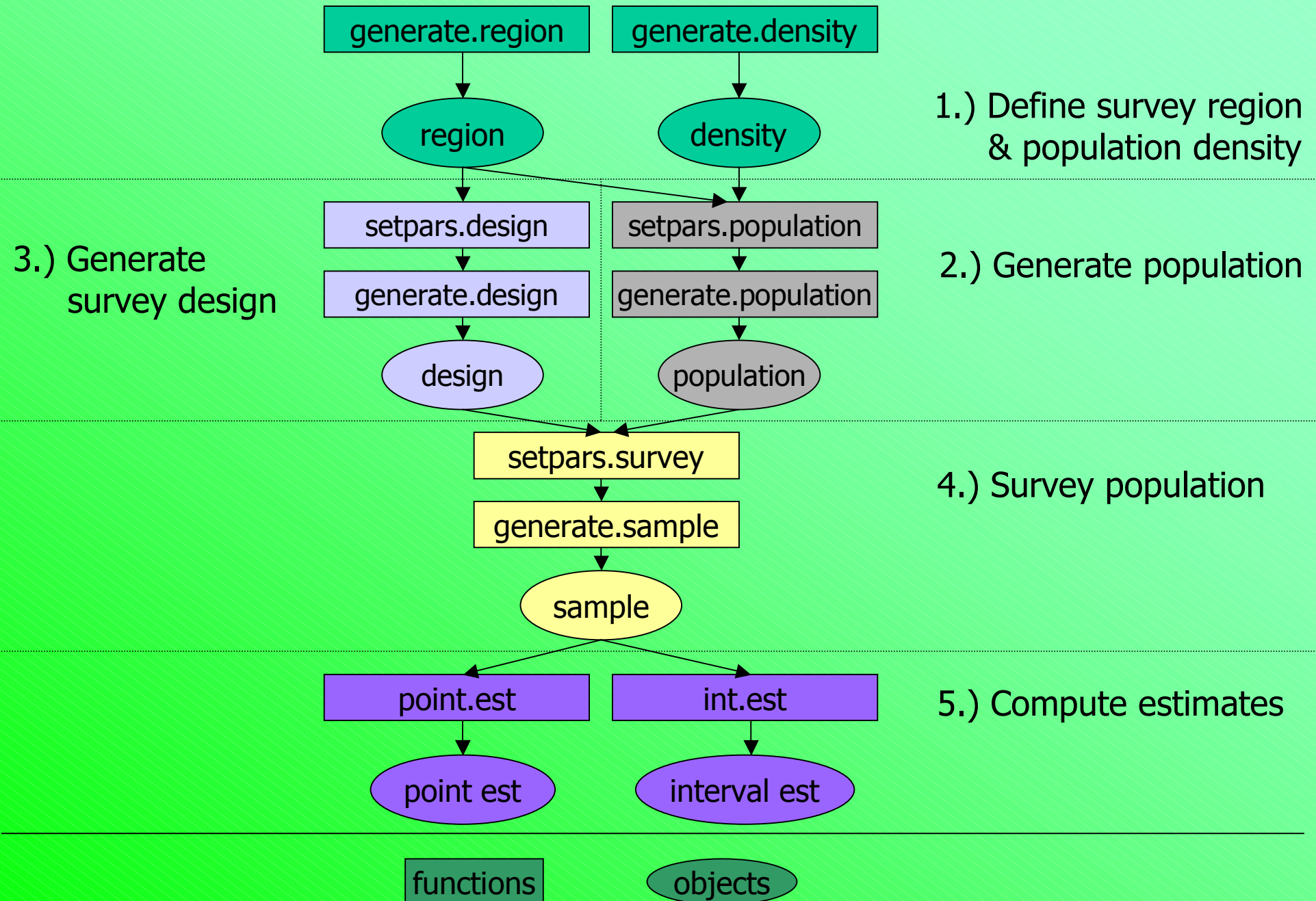
## transects and population



## population density



# Abundance estimation process in *WiSP*



# Estimating abundance

## Currently implemented estimation methods in *WiSP*

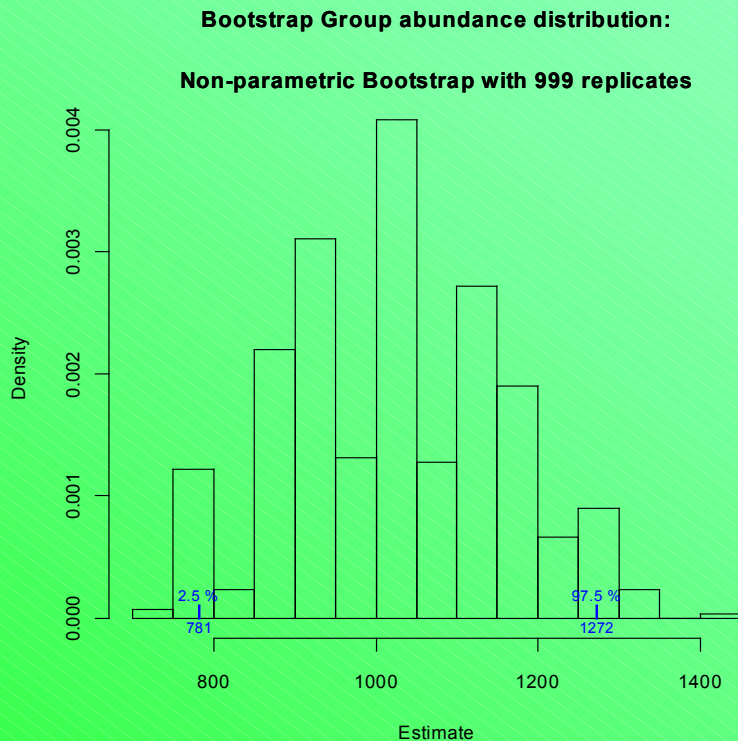
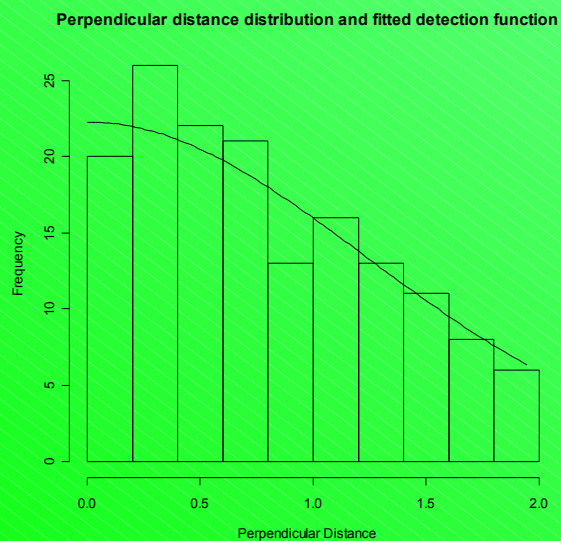
**Point estimates:**  
maximum likelihood  
method of moments

**Interval estimates:**  
asymptotic  
bootstrap  
profile likelihood

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### Example: Line-Transect estimators (True N = 1000)

MLE: 1020  
95% CI: (781, 1272)

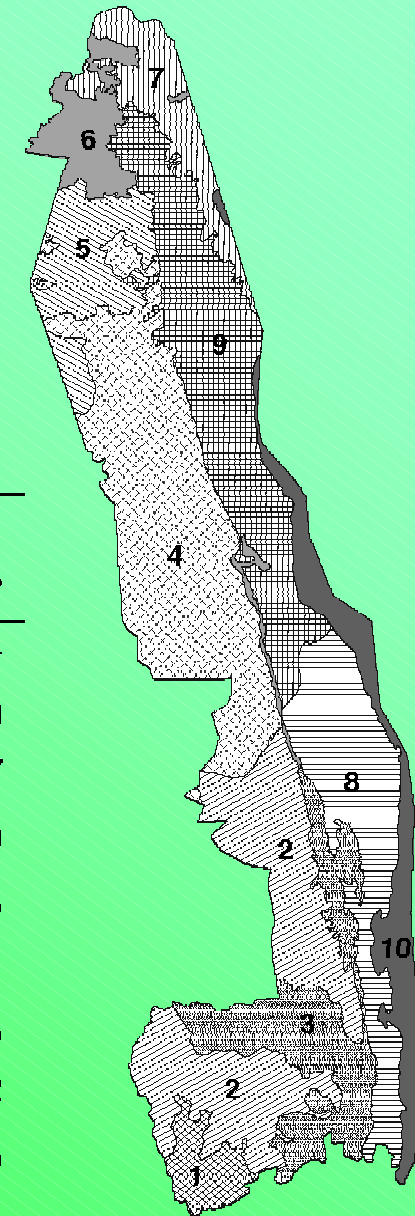


# Point-transect estimates of abundance Brown Hyaena (*Crocuta crocuta*)

Brown Hyaena *Crocuta crocuta*



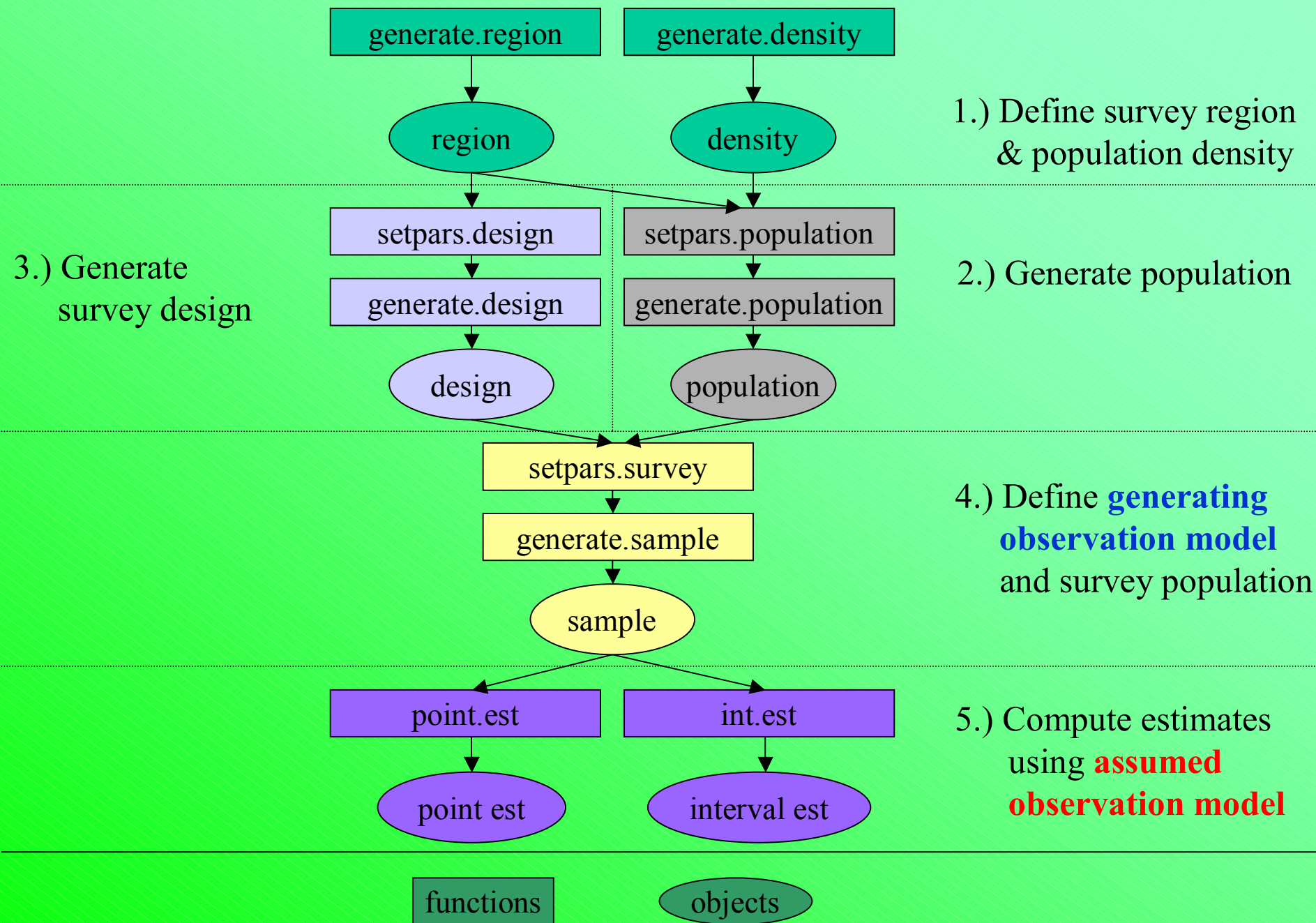
Kruger National Park



Abundance Estimates (Mills, Juritz & Zucchini, 2001)

Habitat	Area	Estimated number	Conf. limits (95%)	
			Lower	Upper
1. Malelane Mountain Bushveld	468	12	–	–
2. Combretum species on granite	3 333	433	312	590
3. Acacia species on bottomland	1 926	407	329	507
4. Mopane-Combretum bush	3 911	723	577	909
5. Mopane-Acacia nigrescens bush	1 222	162	93	305
6. Punda Maria sandveld	680	59	25	101
7. Pafuri rugged veld	997	82	51	103
8. Acacia-nigrescens-Marula sav.	2 241	262	185	382
9. Shrub mopane	3 020	361	273	486
10. Lebombo	1 422	167	106	278

# Summary

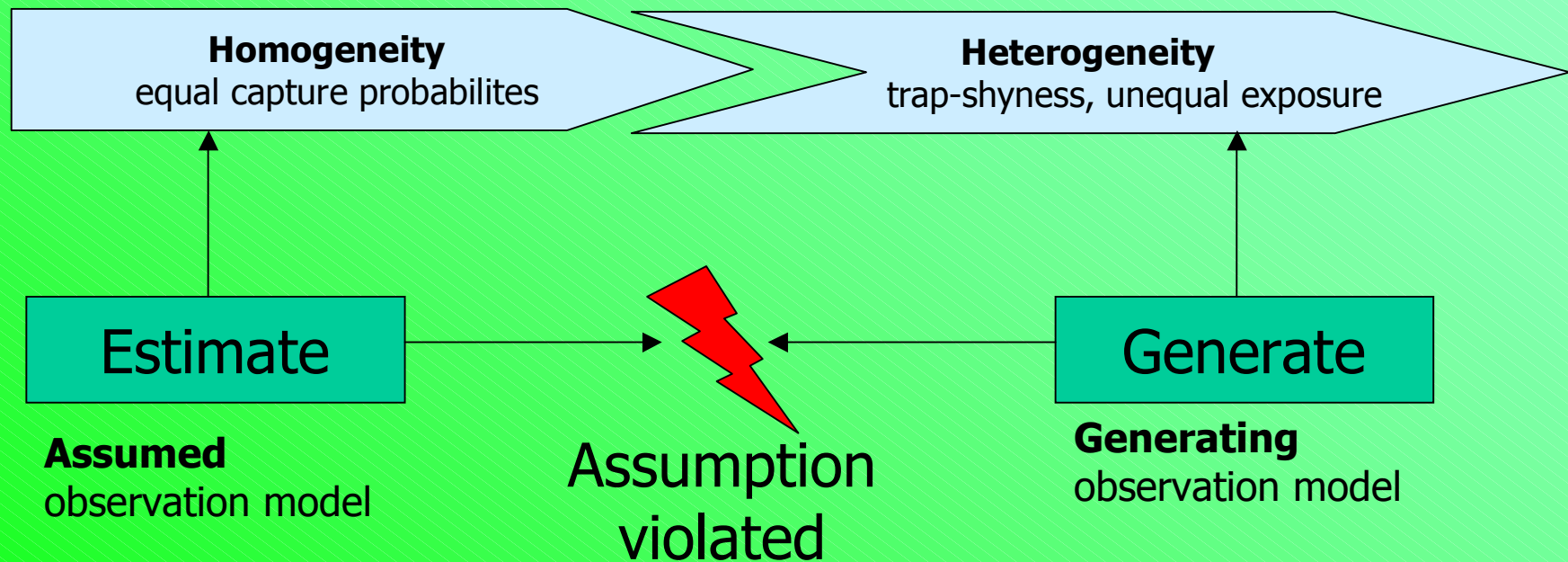


# Assessing sensitivity to assumptions

**Generating observation model** defines the **true** detection/capture probabilities for all animals

**Assumed observation model** is what we use to carry out the estimation

## Mark-recapture method



**Enables sensitivity analysis**

# Example of a sensitivity analysis

**When, why and how do models give the wrong answers?**

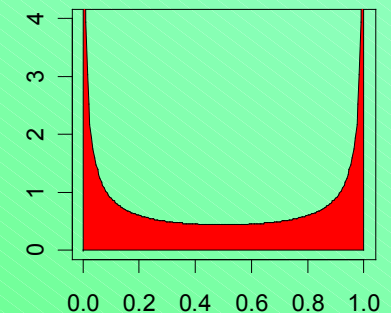
## Simple mark-recapture model

**Assumption:** Capture probability is the same for all animals in all surveys

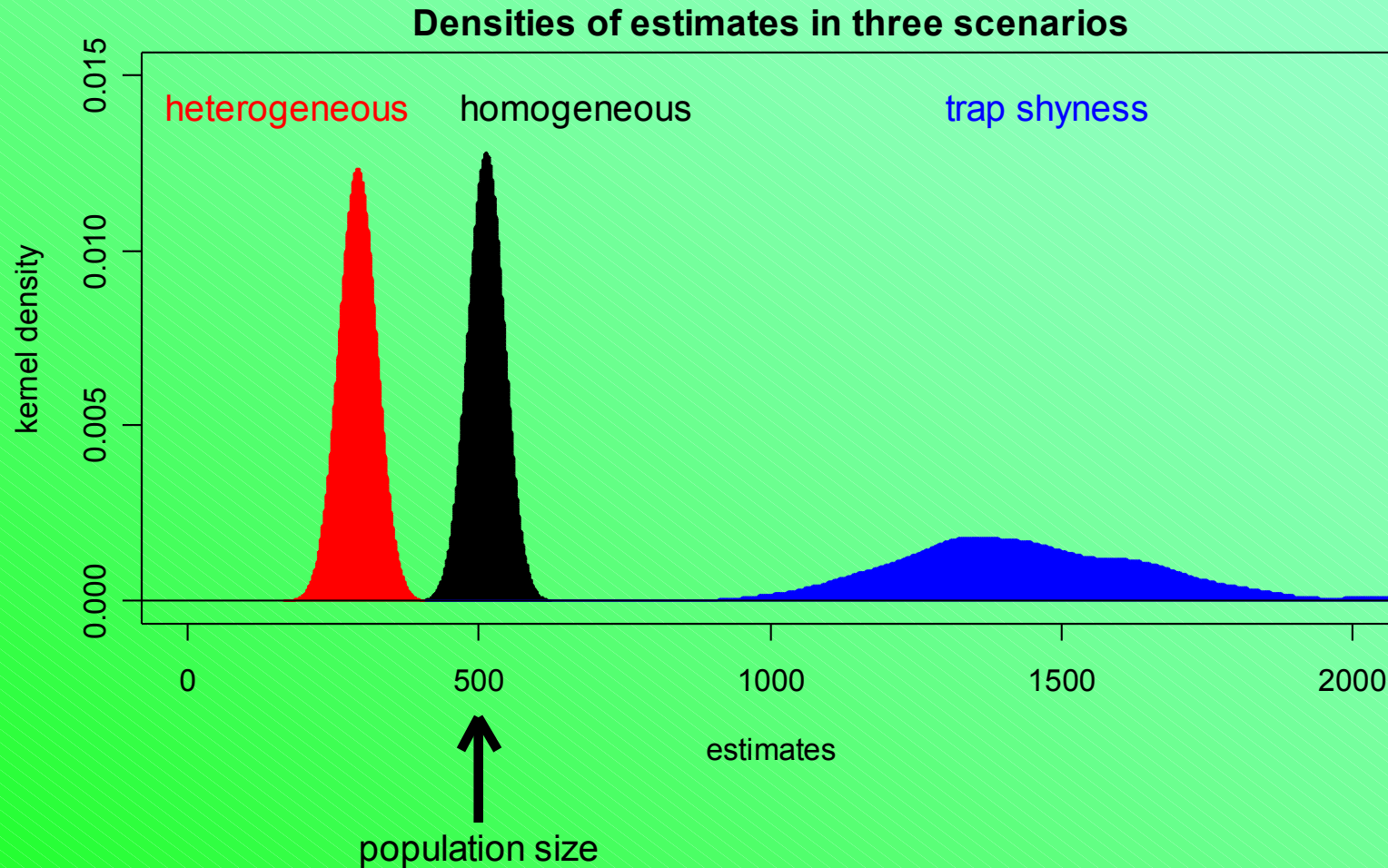
**Violation 1:** Heterogeneity due to exposures  
Capture probabilities differ for different animals

**Violation 2:** Heterogeneity due to trap shyness  
Marked animals are less likely to be recaptured

Capture probabilities density



# Assessing sensitivity to assumptions



**Unequal exposure**

**=>**

**Underestimation of abundance**

**Trap-shyness**

**=>**

**Overestimation of abundance**

# Assessing sensitivity to assumptions

## Application to other methods

### Transect methods

Detection probability depends on distances only

It also depends on other things, e.g. exposure

### Change-In-Ratio method

Detection probability is constant

It depends on catch-effort

It also depends on exposure, types, etc.

# Function and object names

## Prefix (action)

**setpars.survey**  
**generate.design**  
**plot.design**  
**survey**  
**plot.sample**  
**summary.sample**  
**interval.est**  
**etc.**

+

## Suffix (method extension)

**.cir** catch in ratio  
**.cr** capture-recapture  
**.dp** double-platform  
**.lt** line-transect  
**.no** nearest object  
**.pl** plot sampling  
**.pt** point-transect  
**.rm** removal

## Example:

**setpars.survey.pt** Set survey parameters for a **point transect**

# Advantages of programming in R

- **Conceptual convenience**

- Easy to keep an overview of the library
- Encourages structured programming
- Simplifies team programming
- Simplifies maintenance and upgrades

- **Availability of generic functions**

- Functions such as **print**(object) **plot**(object) **summary**(object) identify the class of object and "do the right thing".



is **FREE** and maintained by **SCIENTISTS**

